

# Randomized Algorithms for Matrix Computations

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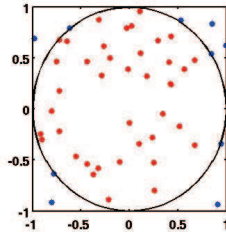
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# Randomized Algorithms

Solve a **deterministic** problem by **statistical sampling**

- Monte Carlo Methods

Von Neumann & Ulam, Los Alamos, 1946



- Simulated Annealing: global optimization

# Application of Randomized Algorithms

- **Astronomy:** Tamás Budavári (Johns Hopkins)  
Classification of galaxies  
Singular Value Decomposition/PCA, subset selection
- **Nuclear Engineering:** Hany Abdel-Khalik (NCSU)  
Model reduction in nuclear fission  
Low-rank approximation
- **Population Genomics:** Petros Drineas (RPI)  
Find SNPs that predict population association  
SVD/PCA, subset selection
- **Software for Machine Learning Applications:**  
Matrix multiplication, linear systems, least squares,  
SVD/PCA, low rank approximation, matrix functions  
Michael Mahoney (Stanford), Ken Clarkson and David Woodruff (IBM Almaden)  
Haim Avron and Christos Boutsidis (IBM Watson), Costas Bekas (IBM Zürich)

# This Talk

## Least squares/regression problems

- Traditional, deterministic algorithms
- A randomized algorithm
  - Krylov space method*
  - Randomized preconditioner*
- **Random sampling** of rows
  - To construct preconditioned matrix*
  - Need: Sampled matrices with low condition numbers*
- A **probabilistic bound** for condition numbers
- Coherence
- Leverage scores

## Least Squares/Regression Problems: Traditional, Deterministic Algorithms

# Least Squares for Dense Matrices

- Given:

*Real  $m \times n$  matrix  $A$  with  $\text{rank}(A) = n$*

*Real  $m \times 1$  vector  $b$*

- Want:  $\min_x \|Ax - b\|_2$  (two-norm)

*Unique solution  $x = A^\dagger b$*


- Direct method:

*QR factorization  $A = QR$   $Q^T Q = I$ ,  $R$  is  $\Delta$*


*Solve  $Rx = Q^T b$*

Operation count:  $\mathcal{O}(mn^2)$

# QR Factorization of Tall & Skinny Matrix



$A = QR$



$Q^T Q = I$

# Least Squares for Dense Matrices

- Given:

*Real  $m \times n$  matrix  $A$  with  $\text{rank}(A) = n$*

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- Want:  $\min_x \|Ax - b\|_2$  (two-norm)

*Unique solution  $x = A^\dagger b$*

- Direct method:

*QR factorization  $A = QR$   $Q^T Q = I$ ,  $R$  is  $\Delta$*

*Solve  $Rx = Q^T b$*

Operation count:  $\mathcal{O}(mn^2)$

- But: Too expensive when  $A$  is large & sparse

QR factorization produces fill-in



# Least Squares for Sparse Matrices: LSQR [Paige & Saunders 1982]

Krylov space method

Iterates  $x_k$  computed with matrix vector multiplications

Residuals decrease (in exact arithmetic)

$$\|b - Ax_k\|_2 \leq \|b - Ax_{k-1}\|_2$$

Convergence fast if condition number  $\kappa(A)$  small

$$\kappa(A) = \|A\|_2 \|A^\dagger\|_2 \geq 1$$

# Accelerating Convergence

Find preconditioner  $P$  with

$\kappa(AP)$  small

Linear system  $Px = rhs$  is easy to solve

Preconditioned least squares problem

Solve  $\min_y \|APy - b\|_2$  by LSQR {fast convergence}

Retrieve solution to original problem:  $x = Py$

The ideal preconditioner

QR factorization  $A = QR$   $Q^T Q = I$ ,  $R$  is  $\Delta$

Preconditioner  $P = R^{-1} \Rightarrow AR^{-1} = Q$

$\kappa(Q) = 1$ : LSQR converges in 1 iteration!!!

But: Construction of preconditioner much too expensive!

# A Randomized Preconditioner for Least Squares Problems

# A Cheaper, Randomized Preconditioner

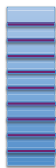
QR factorization from only a **few rows** of  $A$

- **Sample**  $c \geq n$  rows of  $A$ :  $SA$
- “Small” QR factorization

$$SA = Q_S R_S \quad Q_S^T Q_S = I, \quad R_S \text{ is } \triangle$$

- Randomized preconditioner  $R_S^{-1}$

# QR Factorizations of Original and Sampled Matrices



$A$

$=$



$Q$



$R$



$SA$

$=$



$Q_s$



$R_s$

# Blendenpik

[Avron, Maymounkov & Toledo 2010]

- Solve  $\min_z \|Az - b\|_2$
- $A$  is  $m \times n$ ,  $\text{rank}(A) = n$  and  $m \gg n$

{Construct preconditioner}

Sample  $c \geq n$  rows of  $A \rightarrow SA$  {fewer rows}

QR factorization  $SA = Q_S R_S$

{Solve preconditioned problem}

Solve  $\min_y \|AR_S^{-1}y - b\|_2$  with LSQR

Solve  $R_S z = y$   $\{\Delta \text{ system}\}$

Hope:

$AR_S^{-1}$  has almost orthonormal columns

Condition number almost perfect:  $\kappa(AR_S^{-1}) \approx 1$

# From Sampling to Condition Numbers

[Avron, Maymounkov & Toledo 2010]

- *Computed*  
QR decomposition of **sampled matrix**:  $SA = Q_S R_S$
- *Conceptual*  
QR decomposition of **full matrix**:  $A = QR$

The Idea

- 1 **Sampling rows of  $A$**   $\equiv$  Sampling rows of  $Q$
- 2 Condition number of preconditioned matrix:

$$\kappa(AR_S^{-1}) = \kappa(SQ)$$

**We analyze**  $\kappa(SQ)$

Sampled matrices with orthonormal columns

## Random Sampling of Rows



# Random Sampling of Rows

Given: Matrix  $Q$  with  $m$  rows

- 1 Sampling strategies pick **indices**:  
Sample  $c$  indices from  $\{1, \dots, m\}$
- 2 Construct sampled matrix  $SQ$
- 3 Determine **expected value** of  $SQ$

Three sampling strategies:

*Sampling **without** replacement*

*Sampling **with** replacement (*Exactly(c)*)*

***Bernoulli** sampling*

# Uniform Sampling without Replacement

[Gittens & Tropp 2011, Gross & Nesme 2010]

Choose **random** permutation  $k_1, \dots, k_m$  of  $1, \dots, m$   
Pick  $k_1, \dots, k_c$

Properties:

- Picks **exactly**  $c$  indices  $k_1, \dots, k_c$
- Each index is picked **at most once**
- The picks **depend** on each other
- **Random** permutation of  $m$  indices

*A permutation that is equally likely to occur among all  $m!$  permutations*

# Uniform Sampling with Replacement (Exactly(c))

[Drineas, Kannan & Mahoney 2006]

**for**  $t = 1 : c$  **do**

Pick  $k_t$  from  $\{1, \dots, m\}$  with probability  $1/m$   
independently and with replacement

**end for**

Properties:

- Picks exactly  $c$  indices  $k_1, \dots, k_c$
- An index can be picked more than once
- All picks are independent

# Bernoulli Sampling

[Avron, Maymounkov & Toledo 2010, Gittens & Tropp 2011]

```
for  $j = 1 : m$  do  
    Pick  $j$  with probability  $c/m$   
end for
```

Properties:

- Samples each index **at most once**
- **Expected** number of sampled indices:  $c$
- All picks are **independent**

## Construction of Sampled Matrix

- Sampling with and without replacement:

$$SQ = \sqrt{\frac{m}{c}} \begin{pmatrix} \text{row } k_1 \text{ of } Q \\ \vdots \\ \text{row } k_c \text{ of } Q \end{pmatrix}$$

Sampled matrix has  $c$  rows from  $Q$

- Bernoulli sampling:

$$\text{row } j \text{ of } SQ = \sqrt{\frac{m}{c}} \begin{cases} \text{row } j \text{ of } Q & \text{with probability } \frac{c}{m} \\ 0 & \text{with probability } 1 - \frac{c}{m} \end{cases}$$

Sampled matrix has  $m$  rows

Expected number of rows from  $Q$  is  $c$

## Approach towards Expected Value of $SQ$

- Two-norm condition number:

$$\kappa(SQ)^2 = \kappa\left((SQ)^T(SQ)\right)$$

$(SQ)^T(SQ)$  is a symmetric matrix

- Matrix product  $(SQ)^T(SQ)$ : Sum of outer products
- Expected value of one sampled outer product
- Expected value of  $(SQ)^T(SQ)$

## Matrix Product = Sum of Outer Products

$$Q = \begin{pmatrix} x & x \\ x & x \\ x & x \end{pmatrix}$$

Product  $Q^T Q = \begin{pmatrix} x & x & x \\ x & x & x \end{pmatrix} \begin{pmatrix} x & x \\ x & x \\ x & x \end{pmatrix}$

$$= \begin{pmatrix} x \\ x \end{pmatrix} (x \ x) + \begin{pmatrix} x \\ x \end{pmatrix} (x \ x) + \begin{pmatrix} x \\ x \end{pmatrix} (x \ x)$$

= Sum of outer products

# Outer Product Representations

$Q$  has  $m$  rows

$$Q = \begin{pmatrix} r_1 \\ \vdots \\ r_m \end{pmatrix} \quad \text{with} \quad r_1^T r_1 + \cdots + r_m^T r_m = Q^T Q$$

Sampled matrix  $SQ$  has  $c$  rows

$$SQ = \sqrt{\frac{m}{c}} \begin{pmatrix} r_{k_1} \\ \vdots \\ r_{k_c} \end{pmatrix}$$

with

$$\frac{m}{c} \left( r_{k_1}^T r_{k_1} + \cdots + r_{k_c}^T r_{k_c} \right) = (SQ)^T (SQ)$$



## Expected Value of Sampled Matrix

Given: Row  $r_{k_1}$  of  $Q$  from sampling **with** replacement

Expected value of matrix random variable

$$\begin{aligned}\mathbf{E}[r_{k_1}^T r_{k_1}] &= \frac{1}{m} r_1^T r_1 + \cdots + \frac{1}{m} r_m^T r_m \\ &= \frac{1}{m} (r_1^T r_1 + \cdots + r_m^T r_m) \\ &= \frac{1}{m} Q^T Q\end{aligned}$$

Linearity of expected value

$$\begin{aligned}\mathbf{E}[(SQ)^T(SQ)] &= \frac{m}{c} (\mathbf{E}[r_{k_1}^T r_{k_1}] + \cdots + \mathbf{E}[r_{k_c}^T r_{k_c}]) \\ &= \frac{m}{c} \left( \frac{1}{m} Q^T Q + \cdots + \frac{1}{m} Q^T Q \right) = Q^T Q\end{aligned}$$

$(SQ)^T(SQ)$  is **unbiased** estimator of  $Q^T Q$

## Expected Value when Sampling from Matrices with Orthonormal Columns

- Given: Matrix  $Q$  with orthonormal columns,  $Q^T Q = I$
- Matrix  $SQ$  produced by
  - Sampling *with* replacement
  - Sampling *without* replacement
  - *Bernoulli* sampling
- Expected value  $\mathbf{E} [(SQ)^T (SQ)] = Q^T Q = I$ 
  - Cross product of sampled matrix is
  - *Unbiased estimator of identity matrix*
- “In expectation”:  $\kappa(SQ) = 1$ 
  - Expected value of sampled matrix perfectly conditioned

## Where We Are Now in the Talk

- Solution of least squares problems  $\min_x \|Ax - b\|_2$
- Krylov space method + randomized preconditioner
- Condition number of preconditioned matrix:

$$\kappa(SQ) = \|SQ\|_2 \|(SQ)^\dagger\|_2$$

$Q$  has orthonormal columns,  $Q^T Q = I$

- Sampled matrix  $SQ$   
Three different strategies to sample rows from  $Q$
- Expected value of sampled matrix

$$\mathbf{E} \left[ (SQ)^T (SQ) \right] = Q^T Q = I$$

# Issues

- How to **implement** sampling?
- Does sampling **with** replacement really make sense here?
- How large are the **condition numbers** of the sampled matrices?
- How many sampled matrices are **rank deficient**?
- Can we get **bounds** for the condition numbers of the sampled matrices?

*How does the expected value differ from the actually sampled value?*

# How to Implement Uniform Sampling With Replacement

*Sample  $k_t$  from  $\{1, \dots, m\}$  with probability  $1/m$  independently and with replacement*

- [Devroye 1986]

$$\eta = \mathit{rand} \quad \{\text{uniform } [0, 1] \text{ random variable}\}$$
$$k_t = \lfloor 1 + m \eta \rfloor$$

- Matlab:  $k_t = \mathit{randi}(m)$

# Condition Numbers and Rank Deficiency

Sampling  $c$  rows from  $m \times n$  matrix  $Q$  with  $Q^T Q = I$   
 $m = 10^4$ ,  $n = 5$  (30 runs for each value of  $c$ )

Sampled matrices  $SQ$  from three strategies:

*Sampling without replacement*

*Sampling with replacement*

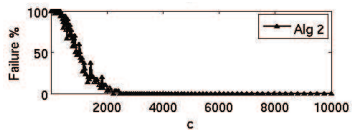
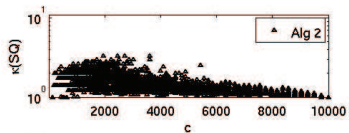
*Bernoulli sampling*

Plots:

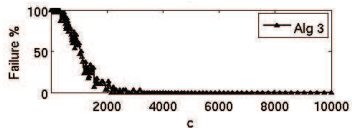
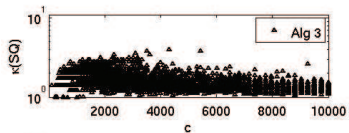
- 1 Condition number of  $SQ$   
 $\kappa(SQ) = \|SQ\|_2 \|(SQ)^\dagger\|_2$  (if  $SQ$  has full column rank)
- 2 Percentage of matrices  $SQ$  that are rank deficient  
( $\kappa(SQ) \geq 10^{16}$ )

# Comparison of Sampling Strategies

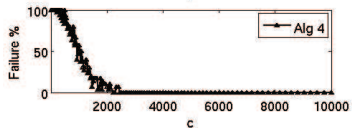
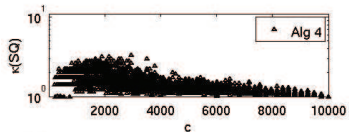
Sampling without replacement



Sampling with replacement (Exactly( $c$ ))



Bernoulli sampling



# Comparison of Sampling Strategies

Sampled matrices  $SQ$  from three strategies:

*Little difference among the sampling strategies*

*Same behavior for small  $c$*

*If  $SQ$  has full rank, then very well conditioned*

$$\kappa(SQ) \leq 10$$

Advantages of sampling **with** replacement

*Fast: Need to generate/inspect only  $c$  values*

*Easy to implement, embarrassingly parallel*

*Replacement does not affect accuracy*

*(for small amounts of sampling)*



A Probabilistic Bound for  
The Condition Number of the Sampled Matrices

## Setup for the Bound

- Given:  $m \times n$  matrix  $Q$  with orthonormal columns
- Sampling  $c$  rows from  $Q$

$$Q = \begin{pmatrix} r_1 \\ \vdots \\ r_m \end{pmatrix} \quad SQ = \sqrt{\frac{m}{c}} \begin{pmatrix} r_{k_1} \\ \vdots \\ r_{k_c} \end{pmatrix}$$

- Unbiased estimator:  $\mathbf{E} [(SQ)^T(SQ)] = Q^T Q = I$
- Sum of  $c$  random matrices:  $(SQ)^T SQ = X_1 + \cdots + X_c$

$$X_t = \frac{m}{c} r_{k_t} r_{k_t}^T \quad 1 \leq t \leq c$$

# Matrix Bernstein Concentration Inequality [Recht 2011]

- $Y_t$  independent random  $n \times n$  matrices with  $\mathbf{E}[Y_t] = 0$
- $\|Y_t\| \leq \tau$  almost surely (two-norm)
- $\rho_t \equiv \max\{\|\mathbf{E}[Y_t Y_t^T]\|, \|\mathbf{E}[Y_t^T Y_t]\|\}$
- Desired error  $0 < \epsilon < 1$
- Failure probability  $\delta = 2n \exp\left(-\frac{3}{2} \frac{\epsilon^2}{\sum_t \rho_t + \tau \epsilon}\right)$

With probability at least  $1 - \delta$

$$\left\| \sum_t Y_t \right\| \leq \epsilon \quad \{\text{Deviation from mean}\}$$

# Applying the Concentration Inequality

- Sampled matrix:

$$(SQ)^T(SQ) = X_1 + \cdots + X_c, \quad X_t = \frac{m}{c} r_{k_t} r_{k_t}^T$$

- Zero mean version:

$$(SQ)^T(SQ) - I = Y_1 + \cdots + Y_c, \quad Y_t = X_t - \frac{1}{c}I$$

- By construction:  $\mathbf{E}[Y_t] = 0$

$$\|Y_t\| \leq \frac{m}{c} \mu, \quad \mathbf{E}[Y_t^2] \leq \frac{m}{c^2} \mu$$

Largest row norm squared:  $\mu = \max_{1 \leq j \leq m} \|r_j\|^2$

With probability at least  $1 - \delta$ ,  $\|(SQ)^T(SQ) - I\| \leq \epsilon$

## Condition Number Bound

- $m \times n$  matrix  $Q$  with orthonormal columns
- Largest row norm of  $Q$  squared:  $\mu = \max_{1 \leq j \leq m} \|r_j\|^2$
- Number of rows to be sampled:  $c \geq n$
- $0 < \epsilon < 1$

Failure probability

$$\delta = 2n \exp\left(-\frac{c}{m\mu} \frac{\epsilon^2}{3 + \epsilon}\right)$$

With probability at least  $1 - \delta$ :

$$\kappa(SQ) \leq \sqrt{\frac{1 + \epsilon}{1 - \epsilon}}$$

# Tightness of Condition Number Bound

*Input:  $m \times n$  matrix  $Q$  with  $Q^T Q = I$  with  
 $m = 10^4$ ,  $n = 5$ ,  $\mu = 1.5 n/m$*

- 1 Exact condition number from sampling with replacement

*Little sampling:  $n \leq c \leq 1000$*

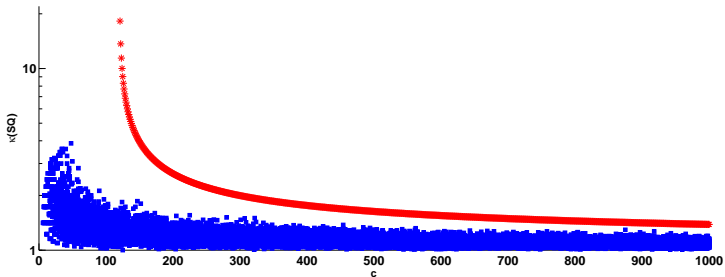
*A lot of sampling:  $1000 \leq c \leq m$*

- 2 Condition number bound  $\sqrt{\frac{1+\epsilon}{1-\epsilon}}$

where success probability  $1 - \delta \equiv .99$

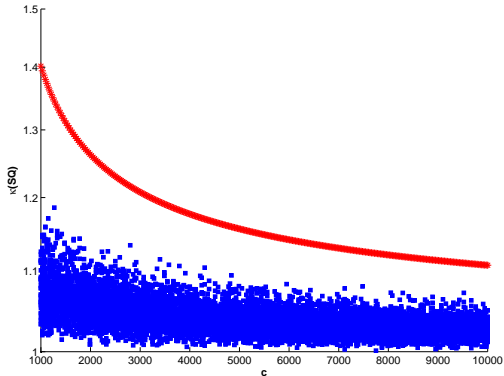
$$\epsilon \equiv \frac{1}{2c} \left( \ell + \sqrt{12c\ell + \ell^2} \right) \quad \ell \equiv \frac{2}{3} (m\mu - 1) \ln(2n/\delta)$$

## Little sampling ( $n \leq c \leq 1000$ )



Bound holds for  $c \geq 93 \approx 2(m\mu - 1) \ln(2n/\delta)/\epsilon^2$

## A lot of sampling ( $1000 \leq c \leq m$ )



Bound predicts correct magnitude of condition number



## Condition Number Bound

- $m \times n$  matrix  $Q$  with orthonormal columns
- Largest row norm of  $Q$  squared:  $\mu = \max_{1 \leq j \leq m} \|r_j\|^2$
- Number of rows to be sampled:  $c \geq n$
- $0 < \epsilon < 1$
- Failure probability

$$\delta = 2n \exp\left(-\frac{c}{m\mu} \frac{\epsilon^2}{3 + \epsilon}\right)$$

With probability at least  $1 - \delta$ :

$$\kappa(SQ) \leq \sqrt{\frac{1 + \epsilon}{1 - \epsilon}}$$

The only **distinction among different**  $m \times n$  matrices  $Q$  with orthonormal columns is  $\mu$

## Conclusions from the Bound

- Correct magnitude for condition number of sampled matrix, even for small matrix dimensions
- Lower bound on number of sampled rows

$$c = \mathcal{O}(m \mu \ln n)$$

- Important ingredient: Largest row norm of  $Q$  squared

$$\mu = \max_{1 \leq j \leq m} \|\text{row } j \text{ of } Q\|^2$$

## Coherence

$$\mu = \max_{1 \leq j \leq m} \|\text{row } j \text{ of } Q\|^2$$

Largest squared row norm of  
matrix  $Q$  with orthonormal columns

# Properties of Coherence

Coherence of  $m \times n$  matrix  $Q$  with  $Q^T Q = I$

$$\mu = \max_{1 \leq j \leq m} \|\text{row } j \text{ of } Q\|^2$$

- $n/m \leq \mu(Q) \leq 1$
- Maximal coherence:  $\mu(Q) = 1$   
At least one column of  $Q$  is a canonical vector
- Minimal coherence:  $\mu(Q) = n/m$   
Columns of  $Q$  are columns of a Hadamard matrix
- Coherence measures “correlation with standard basis”
- Indicator for how well the “mass” of the matrix is distributed

## Coherence in General

- Donoho & Huo 2001  
*Mutual coherence of two bases*
- Candés, Romberg & Tao 2006
- Candés & Recht 2009  
*Matrix completion: Recovering a low-rank matrix by sampling its entries*
- Mori & Talwalkar 2010, 2011  
*Estimation of coherence*
- Avron, Maymounkov & Toledo 2010  
*Randomized preconditioners for least squares*
- Drineas, Magdon-Ismail, Mahoney & Woodruff 2011  
*Fast approximation of coherence*

## Different Definitions

- Coherence of subspace

$Q$  is subspace of  $\mathbb{R}^m$  of dimension  $n$

$P$  orthogonal projector onto  $Q$

$$\mu_0(Q) = \frac{m}{n} \max_{1 \leq j \leq m} \|\text{row } j \text{ of } P\|^2 \quad \left(1 \leq \mu_0 \leq \frac{m}{n}\right)$$

- Coherence of full rank matrix

$A$  is  $m \times n$  with  $\text{rank}(A) = n$

Columns of  $Q$  are orthonormal basis for  $\mathcal{R}(A)$

$$\mu(A) = \max_{1 \leq j \leq m} \|\text{row } j \text{ of } Q\|^2 \quad \left(\frac{n}{m} \leq \mu \leq 1\right)$$

- Reflects difficulty of **recovering** the matrix from **sampling**

# Effect of Coherence on Sampling

*Input:  $m \times n$  matrix  $Q$  with  $Q^T Q = I$*

*Coherence  $\mu = \max_{1 \leq j \leq m} \|\text{row } j \text{ of } Q\|^2$*

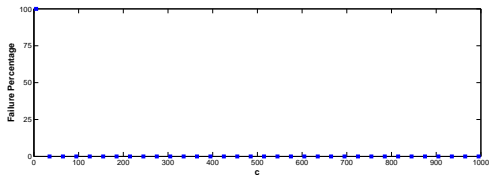
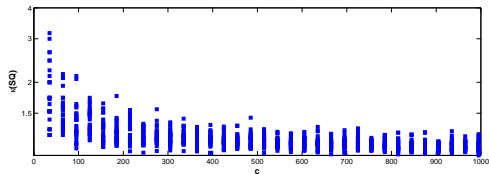
*$m = 10^4, n = 5$*

## Sampling with replacement

① **Low** coherence:  $\mu = 7.5 \cdot 10^{-4} = 1.5 n/m$

② **Higher** coherence:  $\mu = 7.5 \cdot 10^{-2} = 150 n/m$

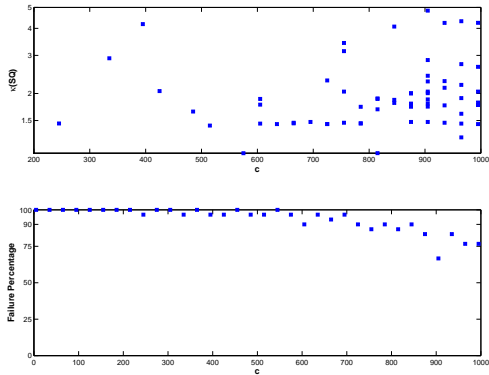
# Low Coherence



Only a **single** rank deficient matrix (for  $c = 5$ )



# Higher Coherence



**Most** matrices rank deficient, when sampling at most 10% of rows

## Improving on Coherence: Leverage Scores

# Leverage Scores

Idea: Use **all** row norms

- $Q$  is  $m \times n$  with orthonormal columns
- **Leverage scores** = squared row norms

$$\ell_k = \|\text{row } k \text{ of } Q\|^2 \quad 1 \leq k \leq m$$

- **Coherence**  $\mu = \max_k \ell_k$
- **Low coherence**  $\approx$  uniform leverage scores
- Leverage scores of **full column rank** matrix  $A$ :  
Columns of  $Q$  are orthonormal basis for  $\mathcal{R}(A)$

$$\ell_k(A) = \|\text{row } k \text{ of } Q\|^2 \quad 1 \leq k \leq m$$

# Statistical Leverage Scores

*Hoaglin & Welsch 1978*

*Chatterjee & Hadi 1986*

- Identify potential outliers in  $\min_x \|Ax - b\|$
- $Hb$ : Projection of  $b$  onto  $\mathcal{R}(A)$  where  $H = A(A^T A)^{-1}A^T$
- **Leverage score**:  $H_{kk} \sim$  influence of  $k$ th data point on LS fit
- **QR decomposition**:  $A = QR$

$$H_{kk} = \|\text{row } k \text{ of } Q\|^2 = \ell_k(A)$$

Application to randomized algorithms: Mahoney & al. 2006–2012

## Leverage Score Bound

- $m \times n$  matrix  $Q$  with orthonormal columns
- Leverage scores

$$l_j = \|\text{row } j \text{ of } Q\|^2 \quad L = \text{diag}(l_1 \dots l_m)$$

- Coherence  $\mu = \max_{1 \leq j \leq m} l_j$
- $0 < \epsilon < 1$

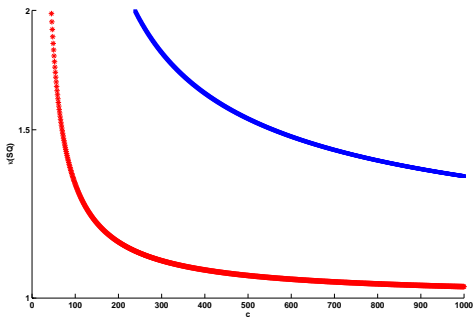
Failure probability

$$\delta = 2n \exp\left(-\frac{3}{2} \frac{c \epsilon^2}{m(3 \|Q^T L Q\|_2 + \mu \epsilon)}\right)$$

With probability at least  $1 - \delta$ :  $\kappa(SQ) \leq \sqrt{\frac{1+\epsilon}{1-\epsilon}}$

# Improvement with Leverage Score Bound

Low coherence:  $\mu = 1.5n/m$ , small amounts of sampling



Leverage score bound vs. Coherence bound

( $m = 10^4$ ,  $n = 4$ ,  $\delta = .01$ )

# Summary

Least squares problems  $\min_z \|Az - b\|_2$

$A$  is  $m \times n$ ,  $\text{rank}(A) = n$  and  $m \gg n$

- Solution by **iterative** Krylov space method LSQR
- Randomized preconditioner
- **Condition number of preconditioned matrix** =  $\kappa(SQ)$ 
  - $Q$  has orthonormal columns,  $SQ$  is sampled matrix*
  - Three strategies to sample rows from  $Q$*
- Bounds for **condition number of sampled matrix  $SQ$** 
  - Explicit, non-asymptotic, predictive even for **small matrix dimensions**
- Sampling accuracy depends on **coherence**
- Tighter bounds: Replace coherence by **leverage scores**

# Existing Work

## Randomized algorithms for least squares

*Drineas, Mahoney & Muthukrishnan 2006*

*Drineas, Mahoney, Muthukrishnan & Sarlós 2006*

*Rokhlin & Tygert 2008*

*Boutsidis & Drineas 2009*

*Blendenpik: Avron, Maymounkov & Toledo 2010*

*LSRN: Meng, Saunders & Mahoney 2011*

## Survey papers for randomized algorithms

*Halko, Martinsson & Tropp 2011*

*Mahoney 2011*

## Graph theory

*Preconditioning for graph Laplacians, graph sparsification*

*Spielman & Teng 2006, Koutis, Miller & Peng 2012, ....*

*Effective resistance = leverage scores*

*Drineas & Mahoney 2010*