
A Matrix-Free, Transpose-Free Norm Estimator

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Motivation

Flow in unsaturated porous media

[Kelley, Kees, Miller, Tocci, 1998]

- Solution of DAE $F(x) = 0$
by Newton iterative method
- To decide whether to update Jacobian
need to estimate $\|A\|$, where $A = [F'(x)]^{-1}$
- A is sparse
- A only accessible as matvec Ax
- Transpose of A not available

Conventional Norm Estimation

Given: real square matrix A

Want: estimate of $\|A\|$

- **p -norm power method estimator**
Generalizes power method on $A^T A$
- **LAPACK 1-norm estimator**
Improvement of 1-norm power method estimator
- **LINPACK-type estimators**
Require factorization of A

Statistical Norm Estimation

A is real $n \times n$ matrix

z is uniformly distributed on unit n -sphere

Dixon 1983: A symmetric positive definite

$$\text{Prob} (z^T A z \geq \epsilon \|A\|_2) \geq 1 - .8\sqrt{n}\epsilon$$

Kuczyński & Woźniakowski 1992

Gudmundsson, Kenney & Laub 1995:

$$E (n \|A z\|_2^2) = \|A\|_F^2$$

Kenney, Laub & Reese 1998: $\|A^{-1}\|_F$

Generating Random Vectors

$$\mathbf{y} = (y_1 \ \dots \ y_n)^T$$

y_i are independent normal $(0, 1)$

$$\|\mathbf{y}\|_2 = \left(\sum_{i=1}^n |y_i|^2 \right)^{1/2}$$

$\mathbf{y}/\|\mathbf{y}\|_2$ uniformly distributed on unit n -sphere

Matlab: `y=randn(n,1); z=y/norm(y)`

Devroye 1986

Calafiore, Dabbene & Tempo 1999

Main Idea

$z = (z_1 \dots z_n)^T$
uniformly distributed on unit n -sphere

$$\text{Prob} \left(\sum_{i=1}^k z_i^2 \leq \epsilon^2 \right) = \frac{B(a, b, \epsilon^2)}{B(a, b, 1)}$$

where $a = \frac{k}{2}$, $b = \frac{n-k}{2}$

$$B(a, b, x) = \int_0^x t^{a-1} (1-t)^{b-1} dt$$

Vector Norm Estimation

Kenney & Laub: $\|v\|_2 = E(|v^T z|)/E_n$

$$E_n = \begin{cases} \frac{(n-2)!!}{(n-1)!!} & \text{if } n \text{ odd} \\ \frac{2}{\pi} \frac{(n-2)!!}{(n-1)!!} & \text{if } n \text{ even} \end{cases}$$

$$\begin{aligned} \text{Prob} \left(\epsilon \|v\|_2 \leq \frac{|v^T z|}{E_n} \leq \frac{\|v\|_2}{\epsilon} \right) \\ \geq 1 - \epsilon \left(\frac{2}{\pi} + 4e^{-1/(4\epsilon^2)} \right) \end{aligned}$$

Our Bounds

$$P = \text{Prob} (|v^T z| \leq \epsilon \|v\|_2)$$

$$\epsilon_1 \sqrt{\frac{n-2}{n-3}} \operatorname{erf} \left(\frac{\epsilon n_1}{\epsilon_1} \right) \leq P \leq \sqrt{\frac{n-1}{n-3}} \operatorname{erf} (\epsilon n_1)$$

where

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$$

$$n_1 = \sqrt{\frac{n-3}{2}}, \epsilon_1 = \sqrt{1 - \epsilon^2}$$

Probabilities for larger n

If $n \geq 1000$ then

$$\text{Prob}(\sqrt{n}|v^T z| \leq 3\|v\|_2) \approx .99$$

$$\text{Prob}\left(\sqrt{n}|v^T z| \geq \frac{\|v\|_2}{100}\right) \approx .92$$

With high probability

$$\sqrt{n}|v^T z| \approx \mu\|v\|_2, \quad 10^{-2} \leq \mu \leq 3$$

Matrix Frobenius Norm Estimation

A is $n \times n$ real matrix

$$\|A\|_F = \left(\sum_{i,j=1}^n |a_{ij}|^2 \right)^{1/2}$$

Two approaches:

- Treat A as a vector: $\|A\|_F = \|\text{vec}(A)\|_2$
- Approximate $\|A\|_F$ by matrix vector products

First Approach

$$\|A\|_F = \|\text{vec}(A)\|_2$$

$\text{vec}(A)$ is $1 \times n^2$

z is uniformly distributed on unit n^2 -sphere

$$\text{Prob}(|\text{vec}(A)z| \leq \epsilon \|A\|_F) = \frac{B(a, b, \epsilon^2)}{B(a, b, 1)}$$

where $a = \frac{1}{2}$, $b = \frac{n^2 - 1}{2}$

$$B(a, b, x) = \int_0^x t^{a-1} (1-t)^{b-1} dt$$

Probabilities for larger n

If $n \geq 1000$ then

$$\text{Prob} (n|\text{vec}(A)z| \leq 3\|A\|_F) \approx .99$$

$$\text{Prob} \left(n|\text{vec}(A)z| \geq \frac{\|A\|_F}{100} \right) \approx .92$$

With high probability

$$n|\text{vec}(A)z| \approx \mu\|A\|_F, \quad 10^{-2} \leq \mu \leq 3$$

Second Approach

Use matrix vector product $\|Az\|_2$
 z is uniformly distributed on unit n -sphere

$$\text{Prob} (\|Az\|_2 \leq \epsilon \|A\|_F) \geq \frac{B(a, b, \epsilon^2)}{B(a, b, 1)}$$

$$\text{Prob} (\|Az\|_2 \geq \epsilon \|A\|_F) \geq 1 - \frac{B(a, b, \epsilon^2)}{B(a, b, 1)}$$

where $a = \frac{1}{2}$, $b = \frac{n-1}{2}$

Probabilities for larger n

If $n \geq 1000$ then

$$\text{Prob} \left(\sqrt{n} \|Az\|_2 \leq 3 \|A\|_F \right) \geq .99$$

$$\text{Prob} \left(\sqrt{n} \|Az\|_2 \geq \frac{\|A\|_F}{100} \right) \geq .92$$

With high probability

$$\sqrt{n} \|Az\|_2 \approx \mu \|A\|_F, \quad 10^{-2} \leq \mu \leq 3$$

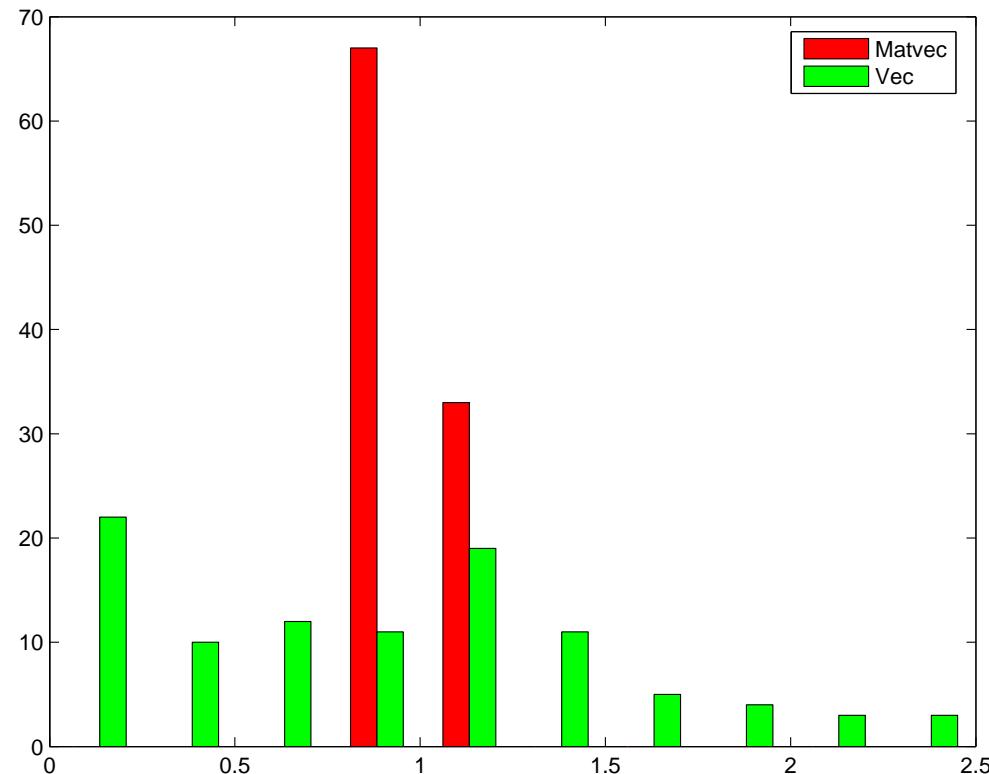
Experiments

- Matrix dimension $n = 1000$
- Matvec:
 $\|A\|_F \approx \sqrt{n}\|Az\|_2$ where z is $n \times 1$
- Vec:
 $\|A\|_F \approx n|\text{vec}(A)z|$ where z is $n^2 \times 1$
- 100 tries for each matrix
- Display:

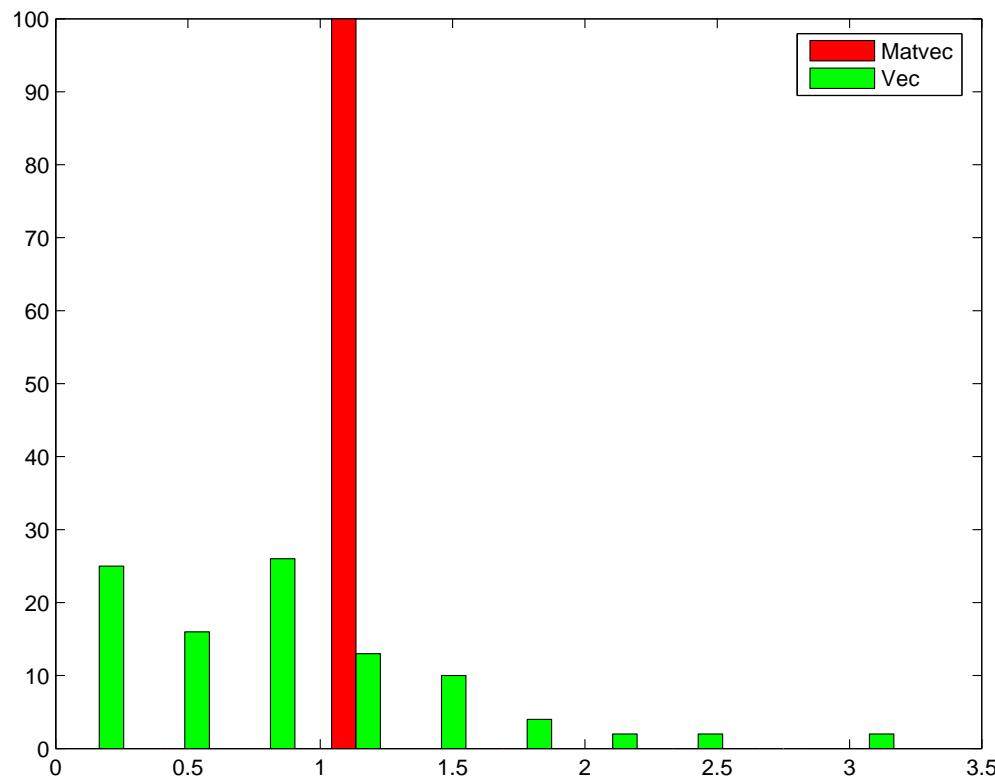
$$\frac{\sqrt{n}\|Az\|_2}{\|A\|_F}$$

$$\frac{n|\text{vec}(A)z|}{\|A\|_F}$$

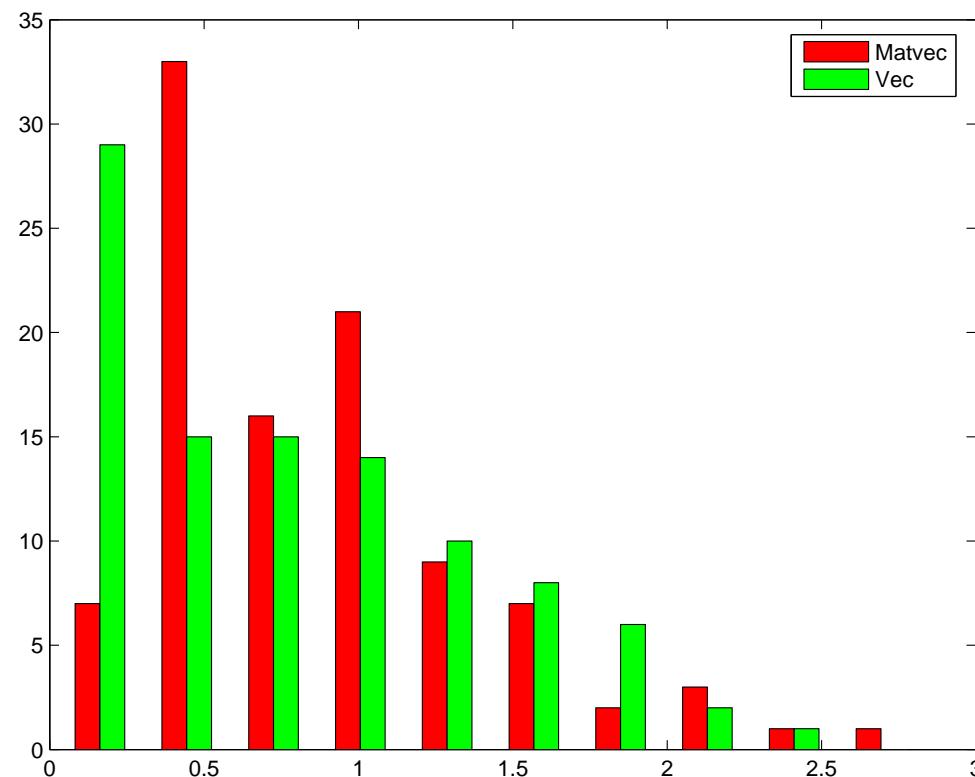
Grcar Matrix



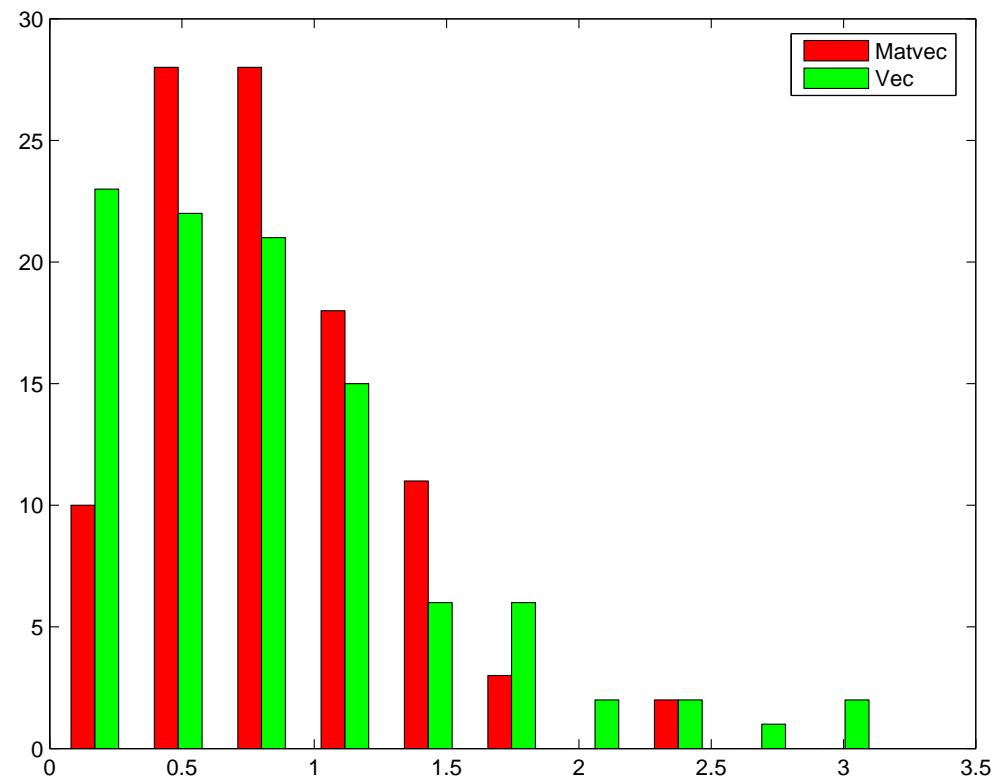
Orthogonal Matrix



Cauchy Matrix



Hilbert Matrix



Experiments

Matrix	Vec	Matvec
Grcar	[.01, 2.3]	[.96, 1.04]
Randn	[.004, 3.2]	[.94, 1.1]
Orthog	[.005, 2.7]	[1, 1]
Chebvand	[.01, 3.1]	[.94, 1.06]
Hilbert	[.001, 2.1]	[.21, 2.2]
Cauchy	[.01, 2.9]	[.18, 2.3]
Rand	[.002, 2.9]	[.49, 1.9]
Clement	[.003, 2.7]	[.98, 1.02]
Chebspec	[.01, 2.5]	[.29, 2.5]

Matvec vs. Vec

Experiments suggest:

- $\|A\|_F \approx \sqrt{n}\|Az\|_2$
 - more accurate
 - easier to compute (1 matvec)
-
- Vec: $\|A\|_F \approx n|\text{vec}(A)z|$
 - less accurate
 - tends to underestimate more

Several Samples

A is a $n \times n$ real matrix

- z uniformly distributed on unit n -sphere

$$\|A\|_F \approx \sqrt{n} \|Az\|_F$$

- Z is $n \times m$ “random” matrix with orthonormal columns

$$\|A\|_F \approx \sqrt{\frac{n}{m}} \|AZ\|_F$$

“Projection” on a subspace

Orthogonal Random Matrices

Birkhoff & Gulati 1979

Stewart 1980

Anderson, Olkin & Underhill 1987

- X is $n \times m$, x_{ij} independent normal (0,1)
- Columns of X lin. indep. (with probability 1)
- QR decomposition

$$X = ZR, \quad Z^*Z = I_m, \quad R_{ii} > 0$$

- Z is invariantly distributed

Experiments

- Tridiagonal matrices of order $n = 1000$
- Matlab `randsvd`
5 different singular value distributions
- Condition numbers: $\|A\|_2\|A^{-1}\|_2 = 10^{16}$
- # samples: $m = 1, 2, 3$
- 100 tries for each matrix and sample
- Display:

$$\sqrt{\frac{n}{m}} \frac{\|AZ\|_F}{\|A\|_F} \quad m = 1, 2, 3$$

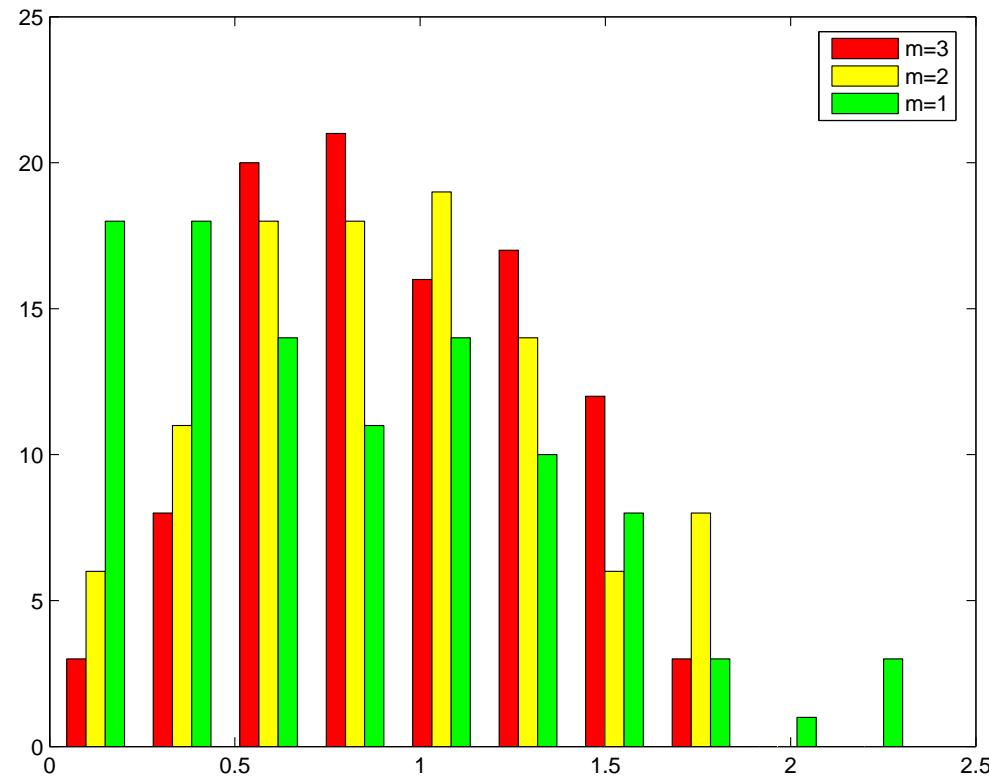
Singular Value Distributions

Singular values $\sigma_1 \geq \dots \geq \sigma_n$

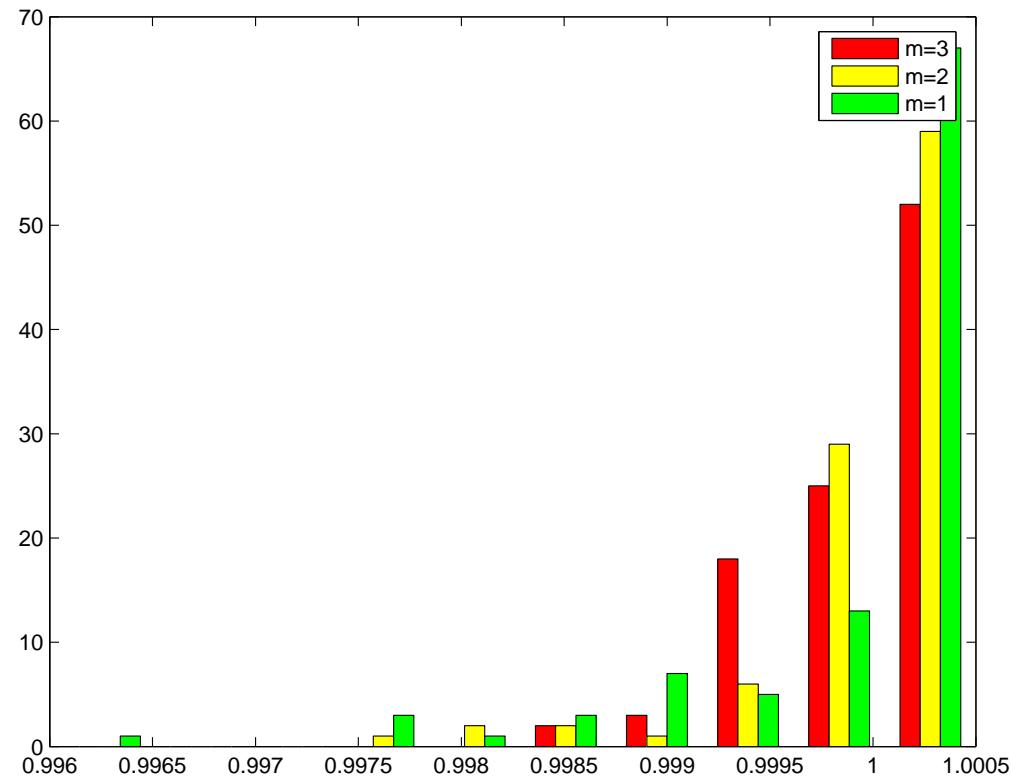
Condition number $\kappa = \sigma_1 / \sigma_n$

- One large singular value:
 $\sigma_1 = 1$, all other $\sigma_i = 1/\kappa$
- One small singular value:
 $\sigma_n = 1/\kappa$, all other $\sigma_i = 1$
- Geometrically distributed singular values:
 $\sigma_i = \kappa^{-(i-1)/(n-1)}$

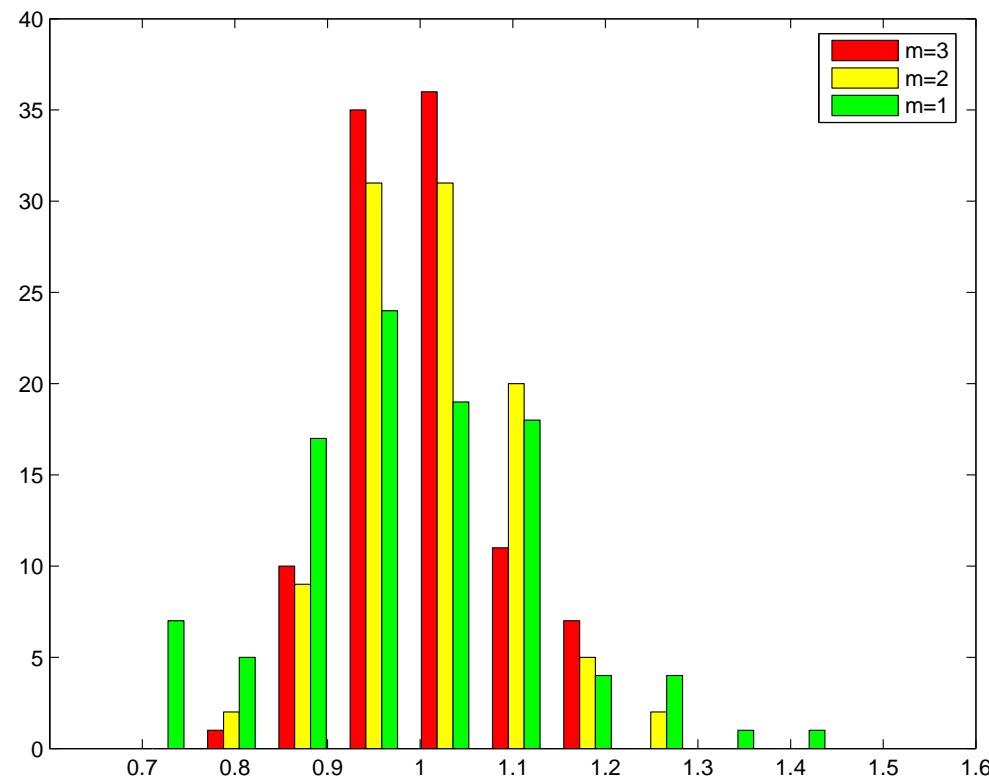
One Large Singular Value



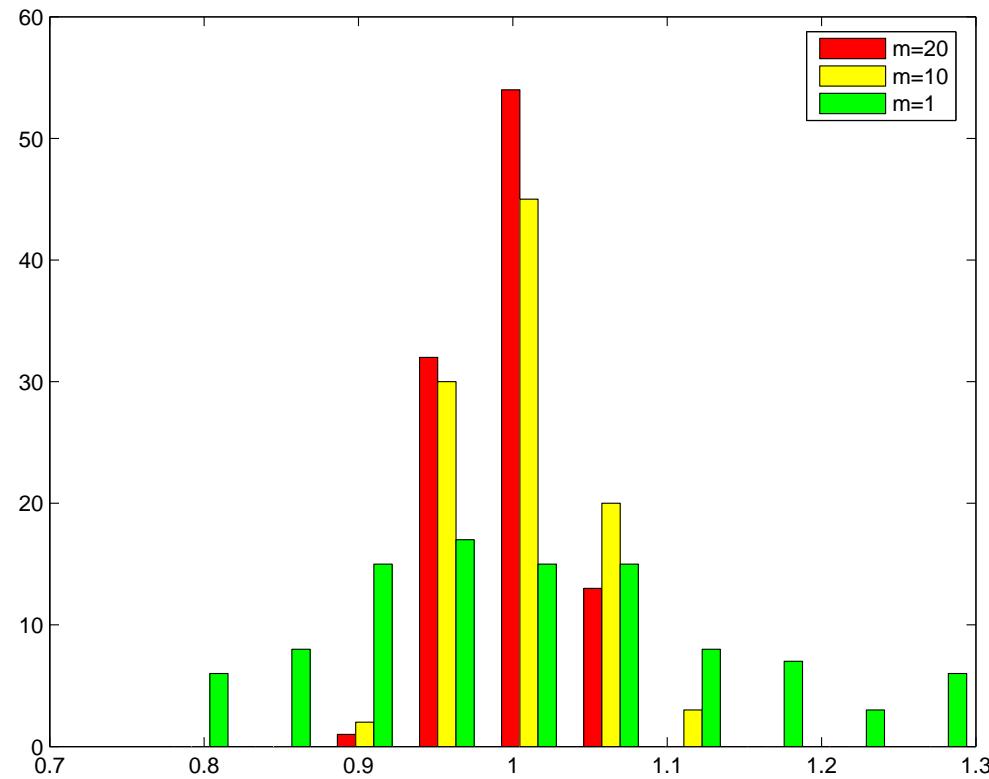
One Small Singular Value



Geometrically Distributed SValues



Many Samples: $m = 1, 10, 20$



Performance of $\sqrt{\frac{n}{m}} \|AZ\|_F$

Experiments suggest:

- A few samples ($m \leq 5$) do not help much
- Many samples ($m \geq 10$) can help more
- Sensitive to singular value distribution
- If A has many large singular values of similar magnitude then for $m = 1$

$$\sqrt{n} \|Az\|_2 \approx (1 \pm 10^{-2}) \|A\|_F$$

Summary

- Statistical norm estimation
- $\|A\|_F \approx \sqrt{n}\|Az\|_2$
 - A is $n \times n$
 - z uniformly distributed on unit n -sphere
- With high probability for $n \geq 1000$
$$\sqrt{n}\|Az\|_2 \approx \mu\|A\|_F, \quad 10^{-2} \leq \mu \leq 3$$
- Works well if A has many large singular values
- m samples: $\|A\|_F \approx \sqrt{\frac{n}{m}}\|AZ\|_F$

Significant improvements only for large m